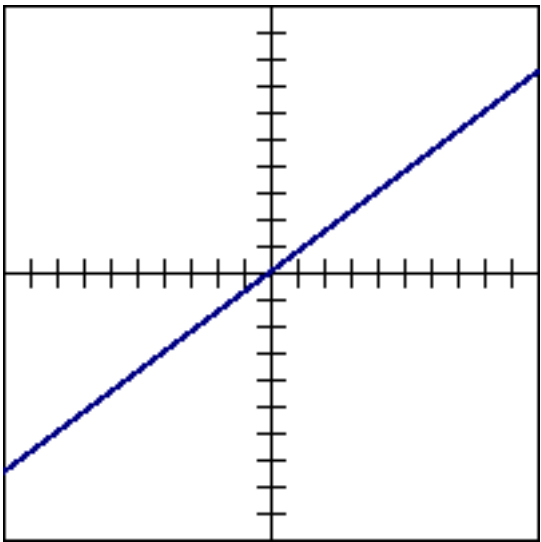


General							
Name	Basis truck						
EEprom Size	701 bytes						
Model Image							
Throttle	Source: THR Trim idle only: No Warning: No Reversed: No						
Trims	Step: Fine Display: Never Extended: No						
Center Beep	None						
Switch Warnings	None						
Pot Warnings	Mode: OFF						
Other	Extended Limits: Yes Display Checklist: No Global Functions: Yes						
Timers	Time	Switch	Countdown	Min.call	Persist		
Tmr1:RijTijd	00:00:00	!L01	Silent	No	OFF		
Tmr2	00:00:00	OFF	Silent	No	OFF		
Tmr3	00:00:00	OFF	Silent	No	OFF		
Modules							
Internal Radio System	Protocol: FrSky XJT (D16) Channels: 1–16 Receiver: 1 Failsafe Mode: Custom CH1:Rijden: 0% CH2:Sturen: 0% CH3:3–bak: Hold CH4: 0% CH5: 0% CH6: 0% CH7:USM S1: 0% CH8:USM S2: 0% CH9:USM 03: 0% CH10:USM 04: 0% CH11:USM 05: 0% CH12:USM 06: 0% CH13:USM 07: 0% CH14:USM 08: 0% CH15:USM 09: 0% CH16:USM 10: 0%						
External Radio Module	Protocol: OFF						
Trainer port	Mode: Master/Jack						
Flight modes							
Flight mode	Switch	F.In	F.Out	TrmR	TrmE	TrmT	TrmA
FM0:Langzaam	----	0	0	0	0	0	0
FM1:Gemiddeld	Li6–	0	0	FM0	FM0	FM0	FM0
FM2:Snel	Li6↑	0	0	FM0	FM0	FM0	FM0
FM3	----	0	0	FM0	FM0	FM0	FM0
FM4	----	0	0	FM0	FM0	FM0	FM0
FM5	----	0	0	FM0	FM0	FM0	FM0
FM6	----	0	0	FM0	FM0	FM0	FM0
FM7	----	0	0	FM0	FM0	FM0	FM0

FM8	----	0	0	FM0	FM0	FM0	FM0		
Global vars	GV1	GV2	GV3	GV4	GV5	GV6	GV7	GV8	GV9
Name									
Unit									
Prec	0._	0._	0._	0._	0._	0._	0._	0._	0._
Min	-1024	-1024	-1024	-1024	-1024	-1024	-1024	-1024	-1024
Max	1024	1024	1024	1024	1024	1024	1024	1024	1024
Popup	N	N	N	N	N	N	N	N	N
Flight mode									
FM0:Langzaam	0	0	0	0	0	0	0	0	0
FM1:Gemiddeld	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
FM2:Snel	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
FM3	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
FM4	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
FM5	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
FM6	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
FM7	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
FM8	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0	FM0
Inputs									
Mixers									
CH1:Rijden	ST2 Weight(+100%) Flight mode(FM2:Snel) += ST2 Weight(+60%) Flight mode(FM1:Gemiddeld) += ST2 Weight(+30%) Flight mode(FM0:Langzaam)								
CH2:Sturen	ST4 Weight(+100%) Flight modes(FM0:Langzaam, FM1:Gemiddeld, FM2:Snel) Delay(u0:d2) Slow(u0:d2)								
CH3:3-bak	Li8 Weight(+100%) Flight modes(FM0:Langzaam, FM1:Gemiddeld, FM2:Snel)								
CH7:USM S1	LSL Weight(+100%) [USMserv1]								
CH8:USM S2	RSL Weight(+100%) [USMserv2]								
CH9:USM 03	ST3 Weight(+100%) Switch(Li2↑) [USMprop3] += ST3 Weight(+50%) Switch(Li2↓) [USMprop3]								
CH10:USM 04	Li9 Weight(+100%) Switch(Li2↑) [USMprop4] += Li9 Weight(+50%) Switch(Li2↓) [USMprop4]								

CH11:USM 05	Re7 Weight(+100%) Switch(Li2↑) [USMprop5] += Re7 Weight(+50%) Switch(Li2↓) [USMprop5]						
CH12:USM 06	Re8 Weight(+100%) Switch(Li2↑) [USMprop6] += Re8 Weight(+50%) Switch(Li2↓) [USMprop6]						
CH13:USM 07	R10 Weight(+100%) Switch(Li2↑) [USMprop7] += R10 Weight(+50%) Switch(Li2↓) [USMprop7]						
CH14:USM 08	Re1 Weight(+100%) [Volume]						
CH15:USM 09	SL1 Weight(+100%) [irServo1]						
CH16:USM 10	SL2 Weight(+100%) [irServo2]						
Outputs							
Channel	Subtrim	Min	Max	Direct	Curve	PPM	Linear
CH1:Rijden	+0.0%	−100.0%	+100.0%	NOR	CV1:Rij	1500	N
CH2:Sturen	+0.0%	−100.0%	+100.0%	NOR	----	1500	N
CH3:3−bak	+0.0%	−100.0%	+100.0%	NOR	----	1500	N
CH7:USM S1	+0.0%	−100.0%	+100.0%	NOR	----	1500	N
CH8:USM S2	+0.0%	−100.0%	+100.0%	NOR	----	1500	N
CH9:USM 03	+0.0%	−100.0%	+100.0%	INV	----	1500	N
CH10:USM 04	+0.0%	−100.0%	+100.0%	INV	----	1500	N
CH11:USM 05	+0.0%	−100.0%	+100.0%	INV	----	1500	N
CH12:USM 06	+0.0%	−100.0%	+100.0%	INV	----	1500	N
CH13:USM 07	+0.0%	−100.0%	+100.0%	INV	----	1500	N
CH14:USM 08	+0.0%	−100.0%	+100.0%	NOR	----	1500	N
CH15:USM 09	+0.0%	−100.0%	+100.0%	NOR	----	1500	N
CH16:USM 10	+0.0%	−100.0%	+100.0%	NOR	----	1500	N
Curves							
CV1:Rij	Custom, [(−100, −75), (0, 0), (100, 75)]						



Logical Switches

L1	ST2 ~ 0
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Special Functions

SF1	Re4↓ – Reset (Timer1)
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Telemetry

Protocol	FrSky S.PORT
RSSI Alarms	Low: < 45; Critical: < 42; <b>Telemetry audio:</b> Enable
Altimetry	<b>Vario source:</b> <b>Vario limits &gt; Sink max:</b> -10; <b>Sink min:</b> -0.5; <b>Climb min:</b> 0.5; <b>Climb max:</b> 10; <b>Center silent:</b> No
Top Bar	<b>Volts source:</b> None; <b>Altitude source:</b> None
Multi sensors	Enable